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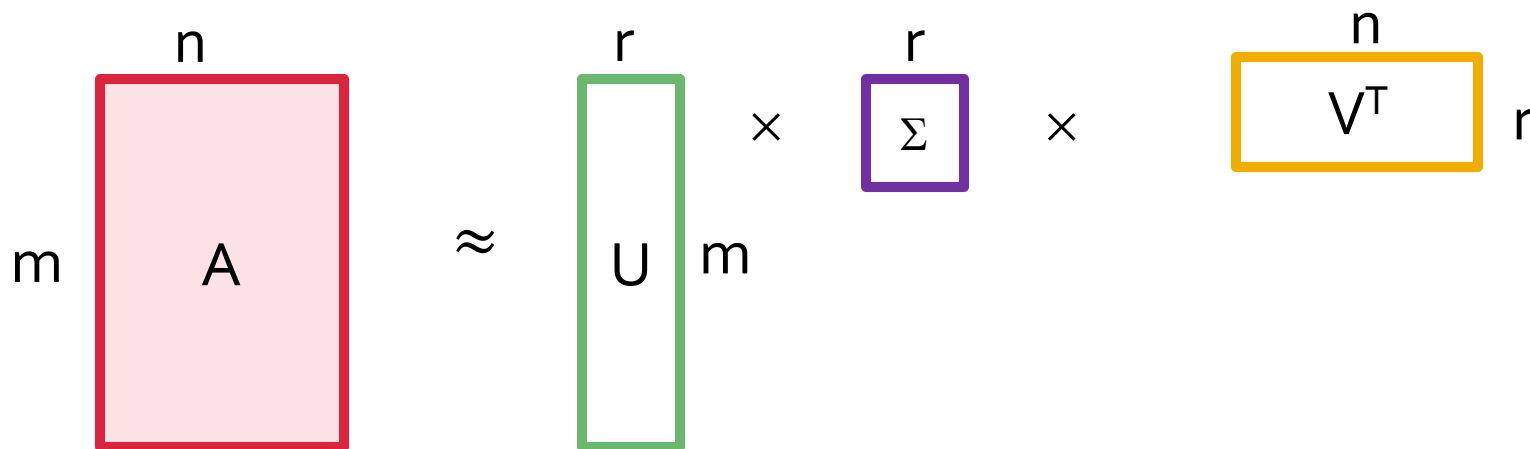
Dimensionality Reduction: SVD & CUR

CS246: Mining Massive Datasets
Jure Leskovec, Stanford University
Charilaos Kanatsoulis, Stanford University
<http://cs246.stanford.edu>



Reducing Matrix Dimension

- Often, our data can be represented by an m -by- n matrix
- And this matrix can be closely approximated by the product of three matrices that share a small common dimension r



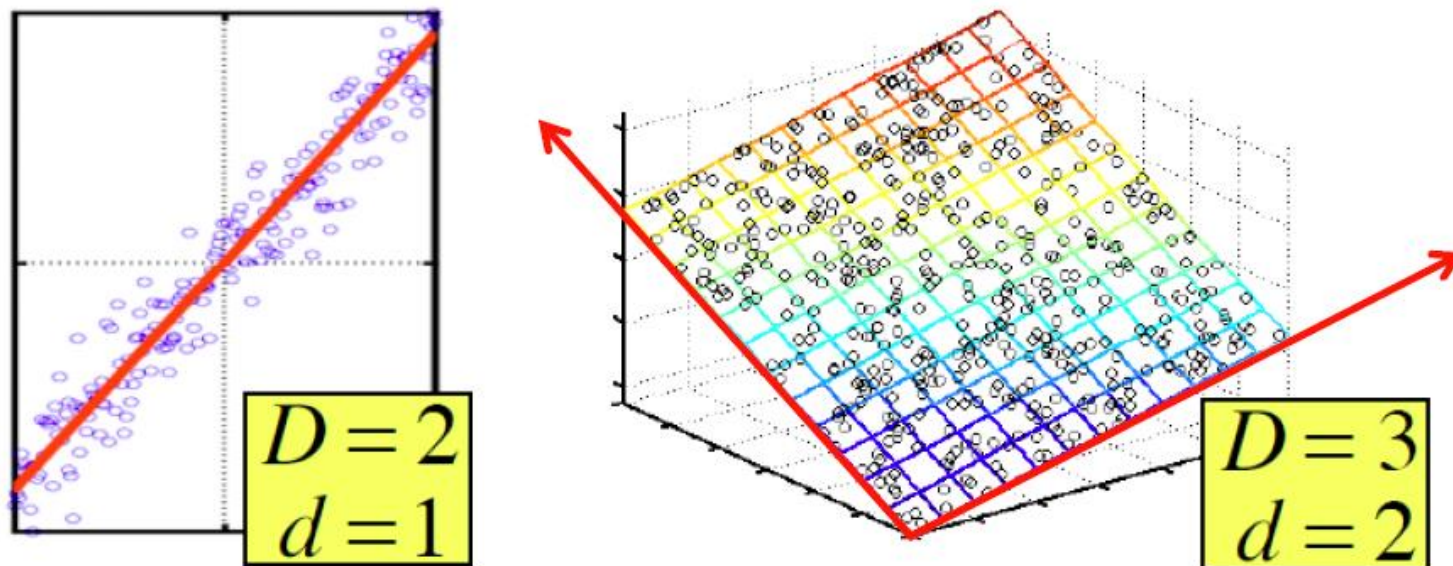
Dimensionality Reduction

- **Compress / reduce dimensionality:**
 - 10^6 rows; 10^3 columns; no updates
 - Random access to any cell(s); **small error: OK**

customer	day	We 7/10/96	Th 7/11/96	Fr 7/12/96	Sa 7/13/96	Su 7/14/96	New representation
ABC Inc.		1	1	1	0	0	[1 0]
DEF Ltd.		2	2	2	0	0	[2 0]
GHI Inc.		1	1	1	0	0	[1 0]
KLM Co.		5	5	5	0	0	[5 0]
Smith		0	0	0	2	2	[0 2]
Johnson		0	0	0	3	3	[0 3]
Thompson		0	0	0	1	1	[0 1]

Note: The above matrix is really “2-dimensional.” All rows can be reconstructed by scaling [1 1 1 0 0] or [0 0 0 1 1]

Dimensionality Reduction

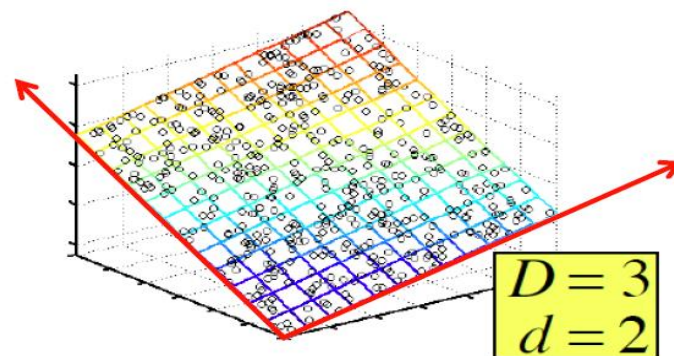
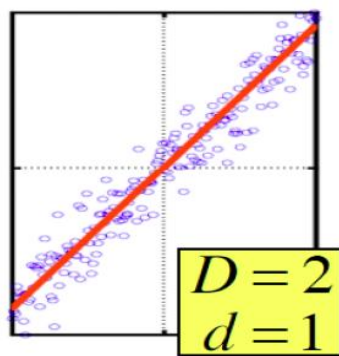


There are hidden, or **latent factors, latent dimensions** that – to a close approximation – explain why the values are as they appear in the data matrix

Dimensionality Reduction

The axes of these dimensions can be chosen by:

- The first dimension is the direction in which the points exhibit the greatest variance
- The second dimension is the direction, orthogonal to the first, in which points show the 2nd greatest variance
- And so on..., until you have enough dimensions that variance is really low



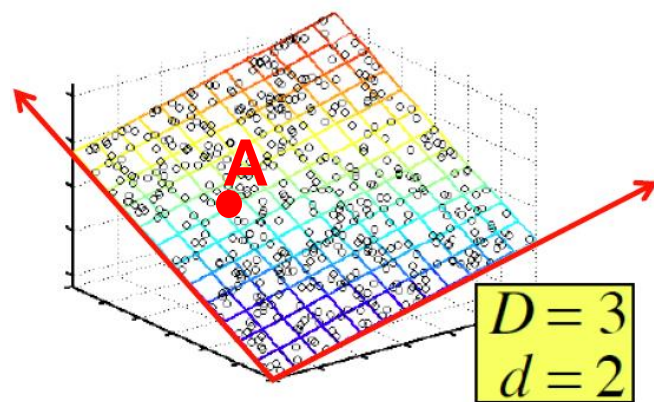
Rank is “Dimensionality”

- **Q:** What is **rank** of a matrix **A**?
- **A:** Number of **linearly independent** rows of **A**
- **Cloud of points in 3D space:**

- Think of point coordinates

as a matrix:
$$\begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix} \begin{matrix} \mathbf{A} \\ \mathbf{B} \\ \mathbf{C} \end{matrix}$$

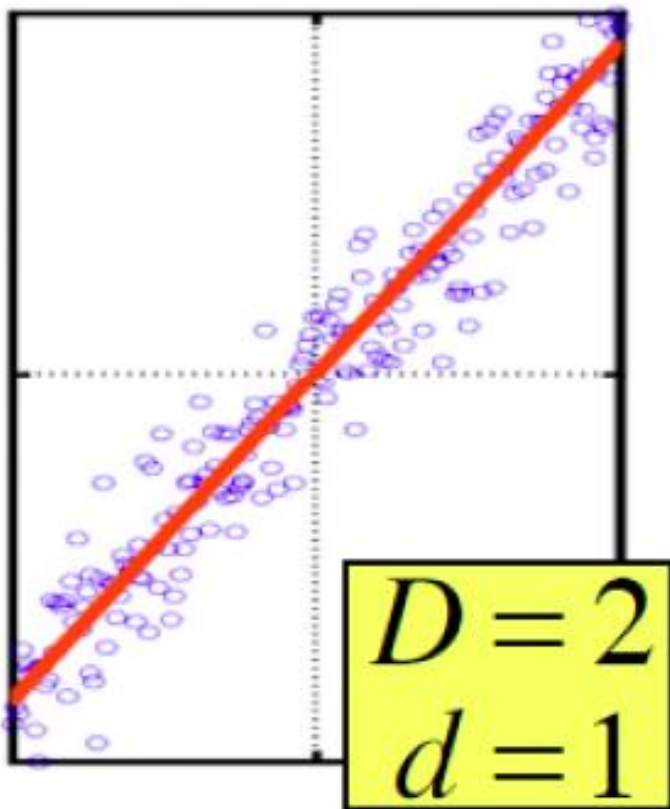
1 row per point:



- **We can rewrite coordinates more efficiently!**
 - Old basis vectors: $[1 \ 0 \ 0]$ $[0 \ 1 \ 0]$ $[0 \ 0 \ 1]$
 - **New basis vectors:** $[1 \ 2 \ 1]$ $[-2 \ -3 \ 1]$
 - Then **A** has new coordinates: $[1 \ 0]$, **B**: $[0 \ 1]$, **C**: $[1 \ -1]$
 - **Notice:** We reduced the number of dimensions/coordinates!

Dimensionality Reduction

- Goal of dimensionality reduction is to discover the axes of data!



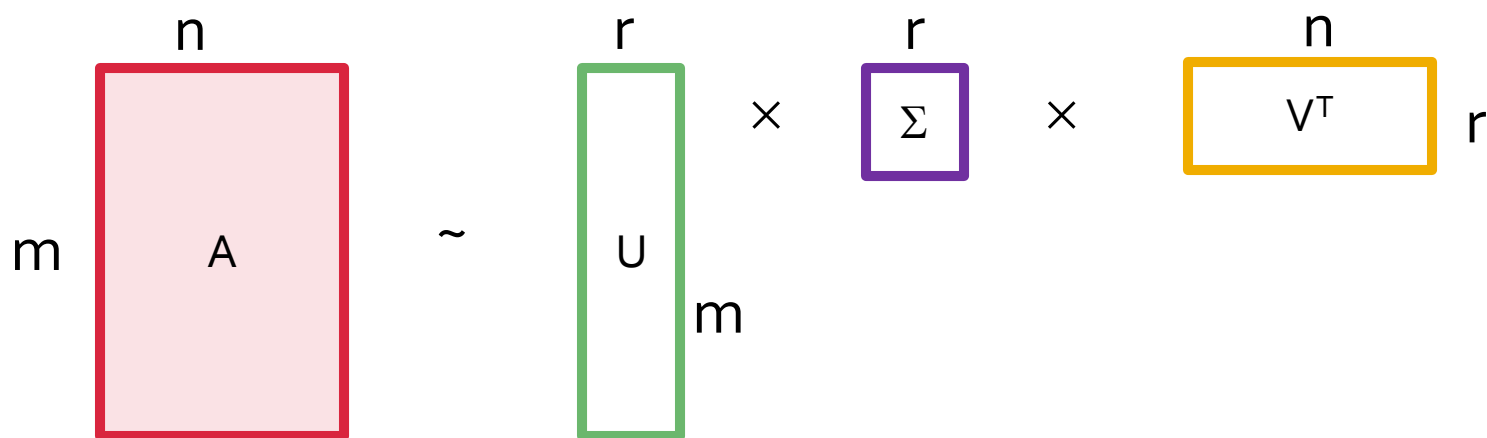
Rather than representing every point with 2 coordinates we represent each point with 1 coordinate (corresponding to the position of the point on the red line).

By doing this we incur a bit of **error** as the points do not exactly lie on the line

SVD: Singular Value Decomposition

Reducing Matrix Dimension

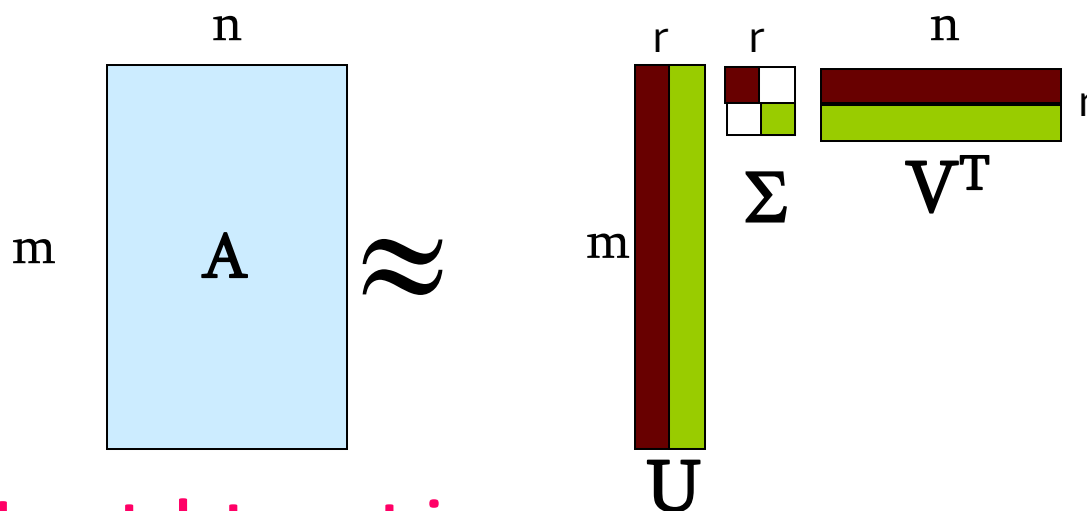
- Gives a decomposition of any matrix into a product of three matrices:



- There are strong constraints on the form of each of these matrices
 - Results in a unique decomposition
- From this decomposition, you can choose any number r of intermediate concepts (latent factors) in a way that minimizes the reconstruction error

SVD – Definition

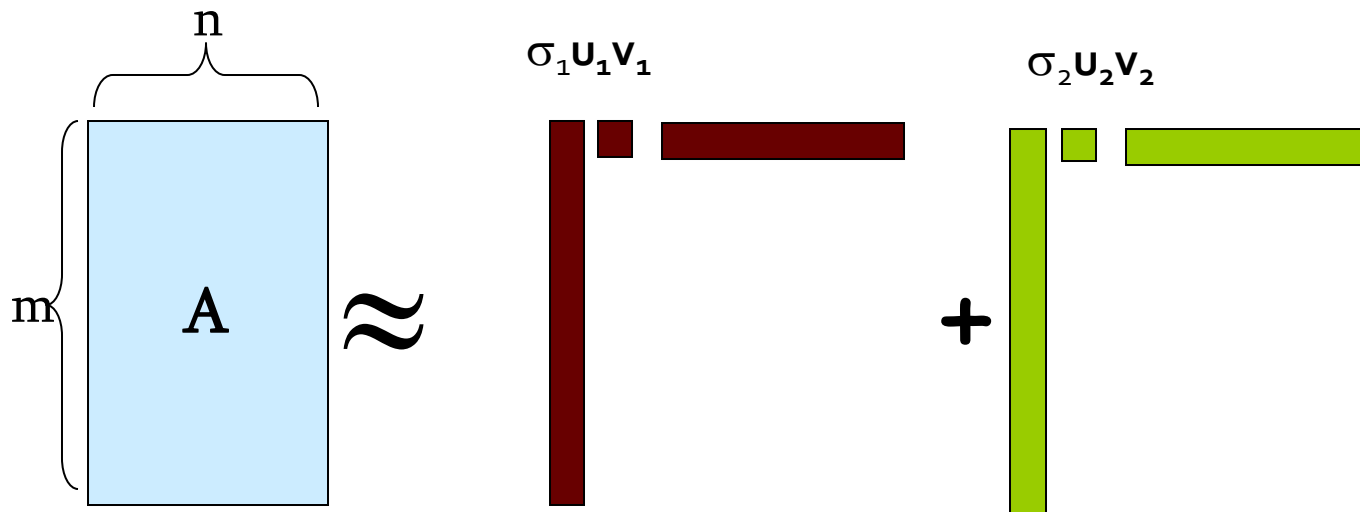
$$\mathbf{A} \approx \mathbf{U}\Sigma\mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^T$$



- **A: Input data matrix**
 - $m \times n$ matrix (e.g., m documents, n terms)
- **U: Left singular vectors**
 - $m \times r$ matrix (m documents, r concepts)
- **Σ : Singular values**
 - $r \times r$ diagonal matrix (strength of each ‘concept’)
(r : rank of the matrix \mathbf{A})
- **V: Right singular vectors**
 - $n \times r$ matrix (n terms, r concepts)

SVD

$$\mathbf{A} \approx \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^T$$



If we set $\sigma_2 = 0$, then the green columns may as well not exist.

$\sigma_i \dots$ scalar
 $\mathbf{u}_i \dots$ vector
 $\mathbf{v}_i \dots$ vector

SVD – Properties

It is **always** possible to decompose a real matrix A into $A = U \Sigma V^T$, where

- U, Σ, V : **unique**
- U, V : **column orthonormal**
 - $U^T U = I; V^T V = I$ (I : identity matrix)
 - (Columns are orthogonal unit vectors)
- Σ : **diagonal**
 - Entries (**singular values**) are **non-negative**, and sorted in decreasing order ($\sigma_1 \geq \sigma_2 \geq \dots \geq 0$)

Nice proof of uniqueness: https://www.cs.cornell.edu/courses/cs322/2008sp/stuff/TrefethenBau_Lec4_SVD.pdf

SVD – Example: Users-to-Movies

- $A = U \Sigma V^T$ - example: Users to Movies

	Matrix	Alien	Serenity	Casablanca	Amelie								
↑	1	1	1	0	0	=	x	x	x				
SciFi	3	3	3	0	0					0.13	0.02	-0.01	
↓	4	4	4	0	0					0.41	0.07	-0.03	
↑	5	5	5	0	0					0.55	0.09	-0.04	
Romance	0	2	0	4	4					0.68	0.11	-0.05	
↓	0	0	0	5	5					0.15	-0.59	0.65	
	0	1	0	2	2	0.07	-0.73	-0.67					
						0.07	-0.29	0.32					
									12.4	0	0		
									0	9.5	0		
									0	0	1.3		
									0.56	0.59	0.56	0.09	0.09
									0.12	-0.02	0.12	-0.69	-0.69
									0.40	-0.80	0.40	0.09	0.09

SVD – Example: Users-to-Movies

■ $A = U \Sigma V^T$ - example: Users to Movies

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SVD – Example: Users-to-Movies

■ $A = U \Sigma V^T$ - example:

U is “user-to-concept” factor matrix

	Matrix	Alien	Serenity	Casablanca	Amelie		SciFi-concept	Romance-concept																																																													
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↓	0	0	0	5	5		0.07	-0.73	-0.67		
	0	1	0	2	2		0.07	-0.29	0.32		

"strength" of the SciFi-concept

↓

12.4	0	0
0	9.5	0
0	0	1.3

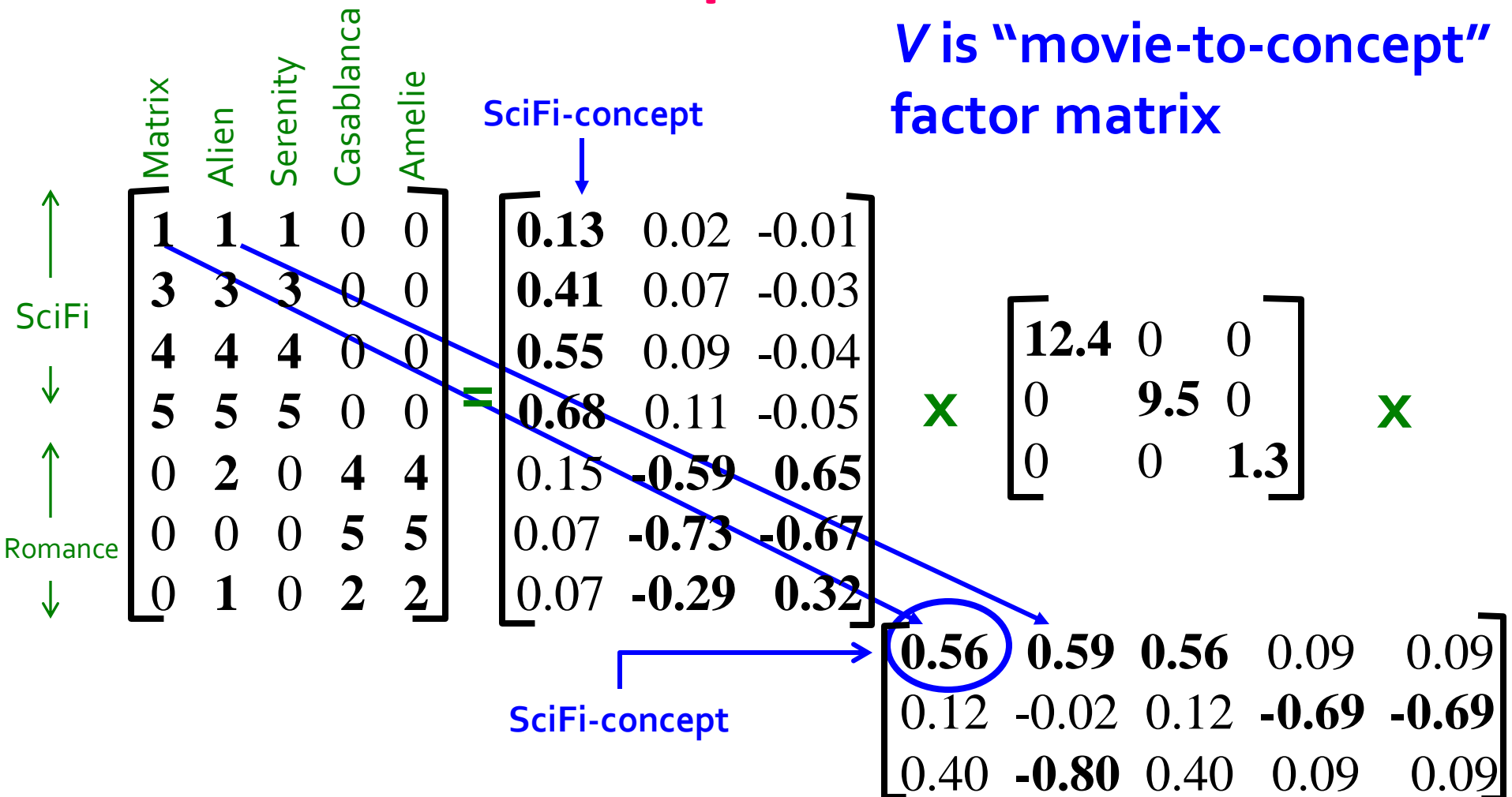
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×

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SVD – Example: Users-to-Movies

■ $A = U \Sigma V^T$ - example:



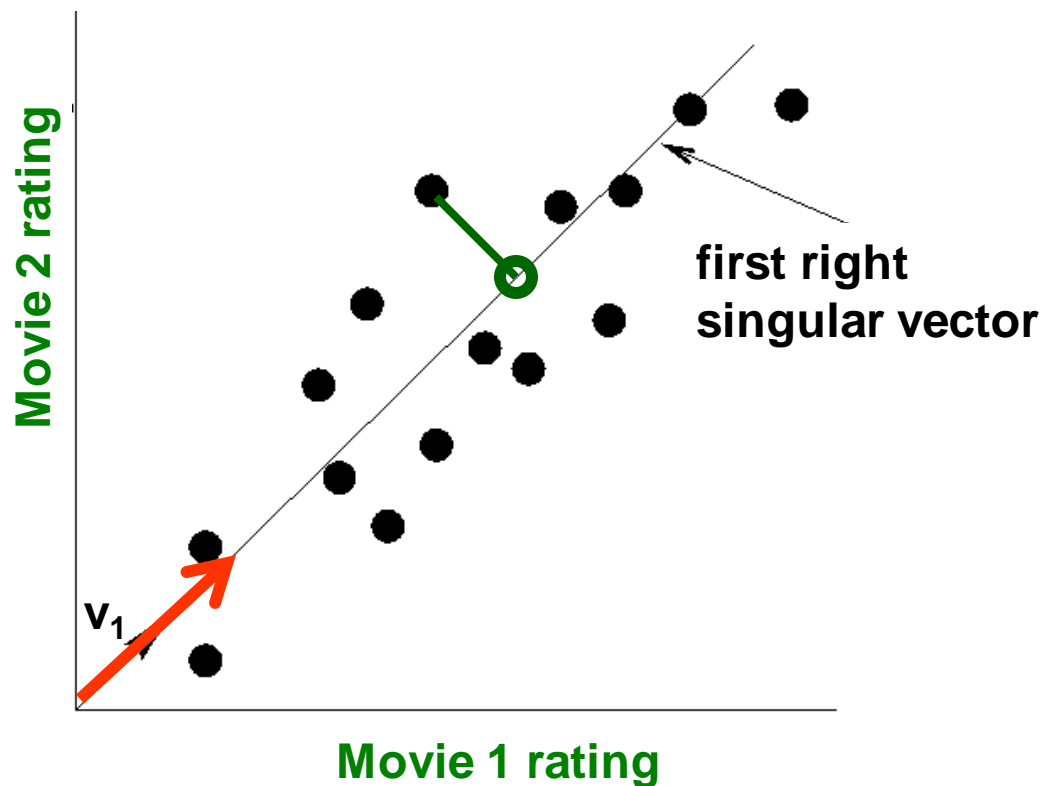
SVD – Interpretation #1

Movies, users and concepts:

- U : user-to-concept matrix
- V : movie-to-concept matrix
- Σ : its diagonal elements:
‘strength’ of each concept

Dimensionality Reduction with SVD

SVD – Dimensionality Reduction

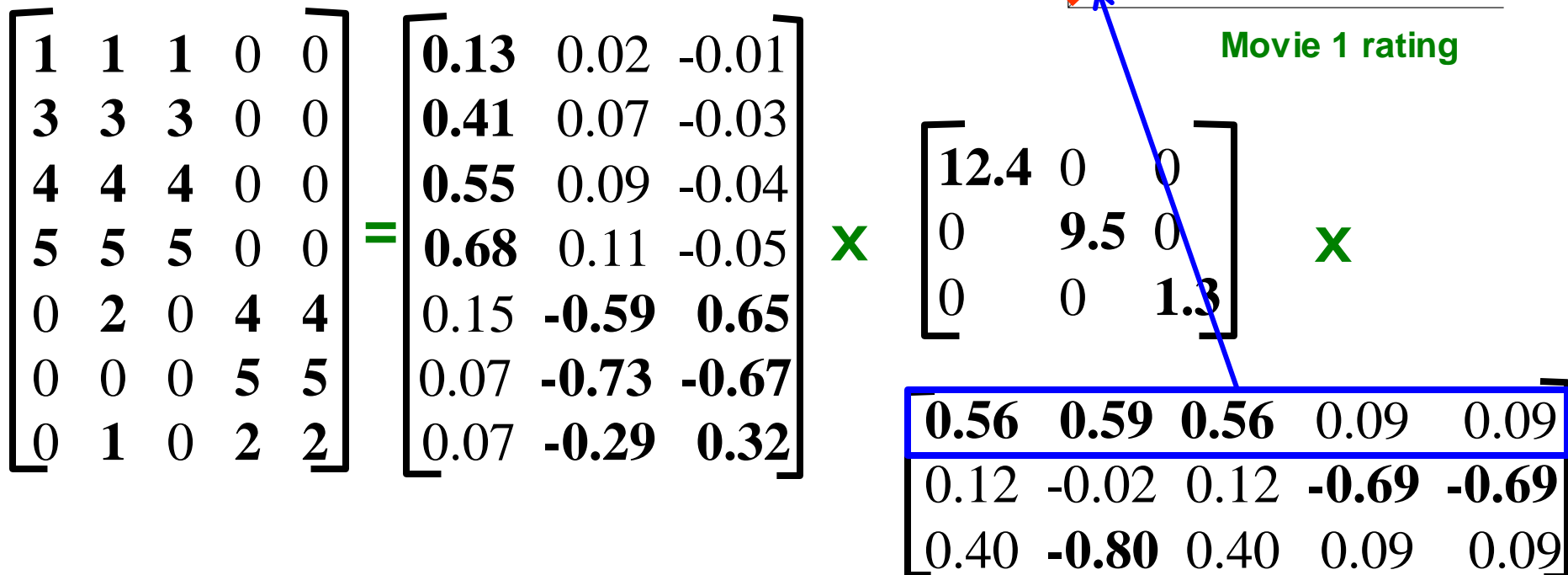


- Instead of using two coordinates (x, y) to describe point positions, let's use only one coordinate
- Point's position is its location along vector v_1

SVD – Dimensionality Reduction

■ $A = U \Sigma V^T$ - example:

- U : “user-to-concept” matrix
- V : “movie-to-concept” matrix

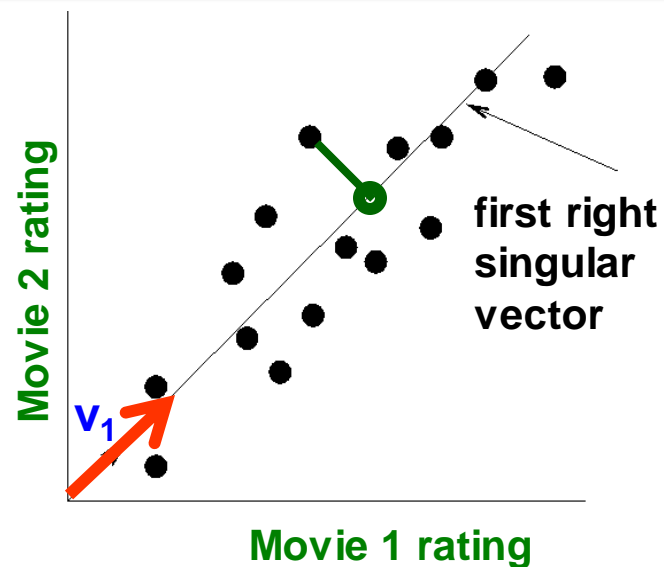


SVD – Dimensionality Reduction

- $A = U \Sigma V^T$ - example:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

variance ('spread')
on the v_1 axis



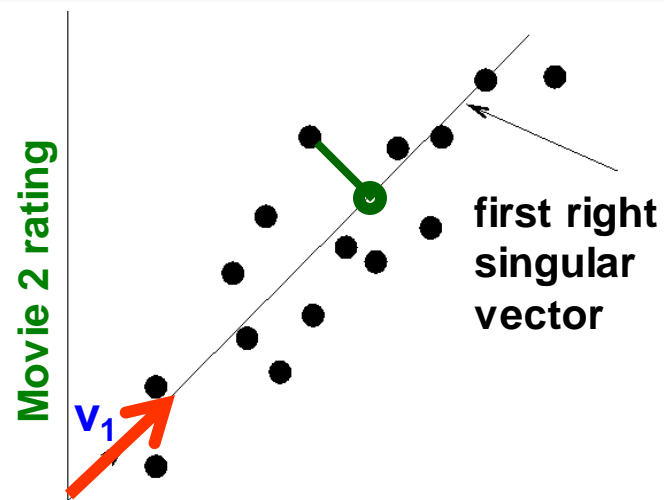
SVD – Dimensionality Reduction

$A = U \Sigma V^T$ - example:

- $U \Sigma$: Gives the coordinates of the points in the projection axis

1	1	1	0	0
3	3	3	0	0
4	4	4	0	0
5	5	5	0	0
0	2	0	4	4
0	0	0	5	5
0	1	0	2	2

Projection of users
on the “Sci-Fi” axis
 $U \Sigma$:



	Movie 1 rating		
1.61	0.19	-0.01	
5.08	0.66	-0.03	
6.82	0.85	-0.05	
8.43	1.04	-0.06	
1.86	-5.60	0.84	
0.86	-6.93	-0.87	
0.86	-2.75	0.41	

SVD – Interpretation #2

More details

- **Q:** How is dim. reduction done?

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

SVD – Interpretation #2

More details

- **Q:** How exactly is dim. reduction done?
- **A:** Set smallest singular values to zero

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix} \times \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & \del{1.3} \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.59 & 0.56 & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -0.69 & -0.69 \\ 0.40 & -0.80 & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

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SVD – Interpretation #2

This is Rank 2 approximation to A. We could also do Rank 1 approx. The larger the rank the more accurate the approximation.

More details

- **Q:** How exactly is dim. reduction done?
- **A:** Set smallest singular values to zero

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More details

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$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} \approx \begin{bmatrix} 0.92 & 0.95 & 0.92 & 0.01 & 0.01 \\ 2.91 & 3.01 & 2.91 & -0.01 & -0.01 \\ 3.90 & 4.04 & 3.90 & 0.01 & 0.01 \\ 4.82 & 5.00 & 4.82 & 0.03 & 0.03 \\ 0.70 & 0.53 & 0.70 & 4.11 & 4.11 \\ -0.69 & 1.34 & -0.69 & 4.78 & 4.78 \\ 0.32 & 0.23 & 0.32 & 2.01 & 2.01 \end{bmatrix}$$

Reconstructed data matrix B

Reconstruction Error is quantified by the Frobenius norm:

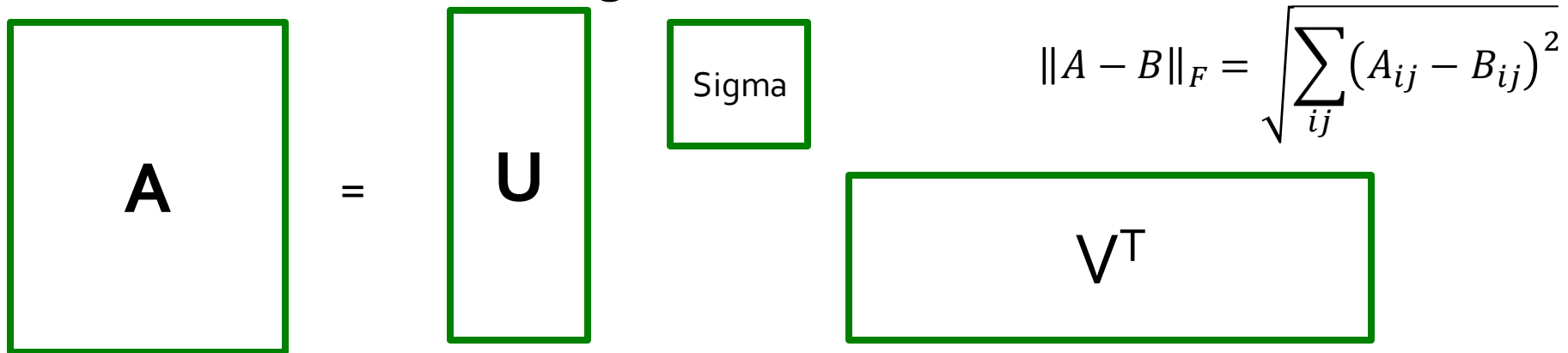
$$\|M\|_F = \sqrt{\sum_{ij} M_{ij}^2}$$

$$\|A-B\|_F = \sqrt{\sum_{ij} (A_{ij}-B_{ij})^2}$$

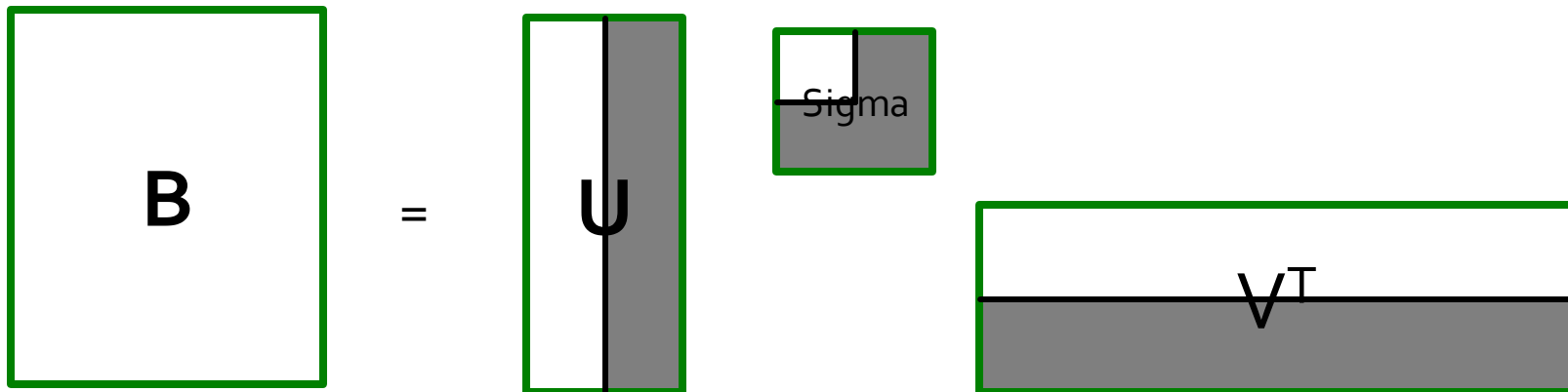
is “small”

SVD – Best Low Rank Approx.

- **Fact: SVD gives ‘best’ axis to project on:**
 - **‘best’** = minimizing the sum of reconstruction errors



B is best approximation of A:



SVD – Best Low Rank Approx.

- Theorem:

Let $A = U \Sigma V^T$ and $B = U S V^T$ where

$S = \text{diagonal } r \times r \text{ matrix}$ with $s_i = \sigma_i$ ($i=1 \dots k$) else $s_i = 0$

then B is a **best** $\text{rank}(B) = k$ approx. to A

What do we mean by “best”:

- B is a solution to $\min_B \|A - B\|_F$ where $\text{rank}(B) = k$

$$\begin{pmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & \\ \vdots & \vdots & \ddots & \\ x_{m1} & & & x_{mn} \end{pmatrix}_{m \times n} = \begin{pmatrix} U & \\ & \text{grey bar} \end{pmatrix}_{m \times r} \begin{pmatrix} \Sigma & \\ & \text{grey bar} \end{pmatrix}_{r \times r} \begin{pmatrix} V^T & \\ & \text{grey bar} \end{pmatrix}_{r \times n}$$

$$\|A - B\|_F = \sqrt{\sum_{ij} (A_{ij} - B_{ij})^2}$$

Refer to the MMDS book for a proof.

SVD – Conclusions so far

- **SVD: $A = U \Sigma V^T$: unique**
 - **U**: user-to-concept factors
 - **V**: movie-to-concept factors
 - Σ : strength of each concept
- **Q: So what's a good value for r (# of latent factors)?**
- Let the *energy* of a set of singular values be the sum of their squares.
- Pick r so the retained singular values have at least 90% of the total energy.
- **Back to our example:**
 - With singular values 12.4, 9.5, and 1.3, total energy = 245.7
 - If we drop 1.3, whose square is only 1.7, we are left with energy 244, or over 99% of the total

How to Compute SVD

Finding Eigenpairs

- How do we actually compute SVD?
- First we need a method for finding the **principal eigenvalue** (the largest one) and the corresponding **eigenvector** of a symmetric matrix
 - M is *symmetric* if $m_{ij} = m_{ji}$ for all i and j
- **Method:**
 - Start with any “guess eigenvector” \mathbf{x}_0
 - Construct $\mathbf{x}_{k+1} = \frac{M\mathbf{x}_k}{\|M\mathbf{x}_k\|}$ for $k = 0, 1, \dots$
 - $\| \dots \|$ denotes the Frobenius norm
 - Stop when consecutive \mathbf{x}_k show little change

Example: Iterative Eigenvector

$$M = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \quad \mathbf{x}_0 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\frac{M\mathbf{x}_0}{\|M\mathbf{x}_0\|} = \begin{pmatrix} 3 \\ 5 \end{pmatrix} / \sqrt{34} = \begin{pmatrix} 0.51 \\ 0.86 \end{pmatrix} = \mathbf{x}_1$$

$$\frac{M\mathbf{x}_1}{\|M\mathbf{x}_1\|} = \begin{pmatrix} 2.23 \\ 3.60 \end{pmatrix} / \sqrt{17.93} = \begin{pmatrix} 0.53 \\ 0.85 \end{pmatrix} = \mathbf{x}_2$$

.....

Finding the Principal Eigenvalue

- Once you have the principal eigenvector \mathbf{x} , you find its eigenvalue λ by $\lambda = \mathbf{x}^T M \mathbf{x}$.
 - **In proof:** We know $\mathbf{x}\lambda = M\mathbf{x}$ if λ is the eigenvalue; multiply both sides by \mathbf{x}^T on the left.
 - Since $\mathbf{x}^T \mathbf{x} = 1$ we have $\lambda = \mathbf{x}^T M \mathbf{x}$
- **Example:** If we take $\mathbf{x}^T = [0.53, 0.85]$, then

$$\lambda = [0.53 \ 0.85] \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 0.53 \\ 0.85 \end{bmatrix} = 4.25$$

Finding More Eigenpairs

- Eliminate the portion of the matrix M that can be generated by the first eigenpair, λ and \mathbf{x} :

$$M^* := M - \lambda \mathbf{x} \mathbf{x}^T$$

- Recursively find the principal eigenpair for M^* , eliminate the effect of that pair, and so on

- **Example:**

$$M^* = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} - 4.25 \begin{bmatrix} 0.53 \\ 0.85 \end{bmatrix} \begin{bmatrix} 0.53 & 0.85 \end{bmatrix} = \begin{bmatrix} -0.19 & 0.09 \\ 0.09 & 0.07 \end{bmatrix}$$

How to Compute the SVD

- Start by supposing $A = U\Sigma V^T$
- $A^T = (U\Sigma V^T)^T = (V^T)^T \Sigma^T U^T = V\Sigma U^T$
 - **Why?** (1) Rule for transpose of a product; (2) the transpose of the transpose and the transpose of a diagonal matrix are both the identity functions
- $A^T A = V\Sigma U^T U \Sigma V^T = V\Sigma^2 V^T$
 - **Why?** U is orthonormal, so $U^T U$ is an identity matrix
 - Also note that Σ^2 is a diagonal matrix whose i -th element is the square of the i -th element of Σ
- $A^T A V = V\Sigma^2 V^T V = V\Sigma^2$
 - **Why?** V is also orthonormal

Computing the SVD –(2)

- Since $A^T A = V \Sigma^2 V^T \rightarrow A^T A V = V \Sigma^2$
 - **Note** that therefore the i -th column of V is an eigenvector of $A^T A$, and its eigenvalue is the i -th element of Σ^2
- Thus, we can find V and Σ by finding the eigenpairs for $A^T A$
 - Once we have the eigenvalues in Σ^2 , we can find the singular values by taking the square root of these eigenvalues
- Symmetric argument, $A A^T$ gives us U

SVD – Complexity

- **To compute the full SVD using specialized methods:**
 - $O(nm^2)$ or $O(n^2m)$ (whichever is less)
- **But:**
 - Less work, if we just want singular values
 - or if we want the first k singular vectors
 - or if the matrix is sparse
- **Implemented in** linear algebra packages like
 - LINPACK, Matlab, SPlus, Mathematica ...

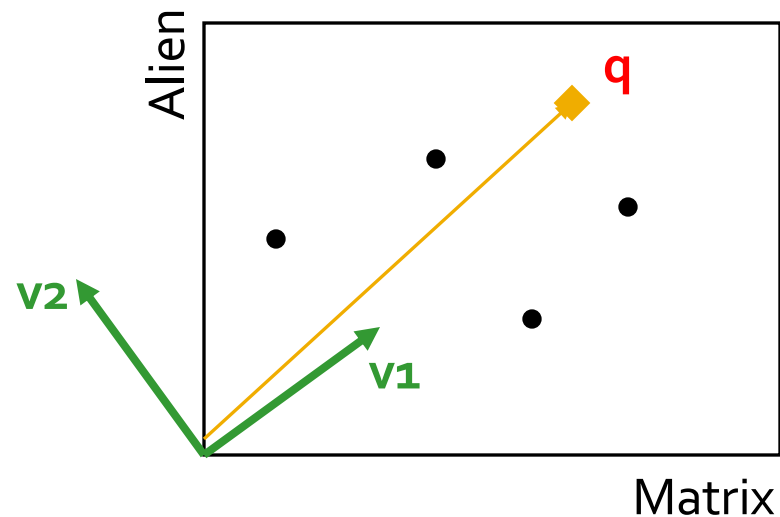
Example of SVD

Case study: How to query?

- **Q: Find users that like 'Matrix'**
- **A: Map query into a 'concept space' – how?**

$$q = \begin{bmatrix} \text{Matrix} \\ 5 \\ \text{Alien} \\ 0 \\ \text{Serenity} \\ 0 \\ \text{Casablanca} \\ 0 \\ \text{Amelie} \\ 0 \end{bmatrix}$$

Project into concept space:
Inner product with each
'concept' vector v_i

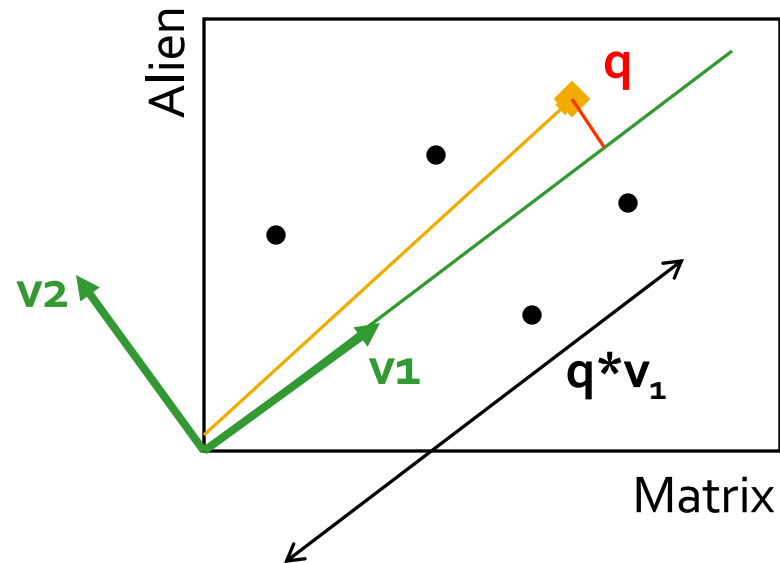


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Project into concept space:
Inner product with each
'concept' vector v_i



Case study: How to query?

Compactly, we have:

$$\mathbf{q}_{\text{concept}} = \mathbf{q} \mathbf{V}$$

E.g.:

$$\mathbf{q} = \begin{bmatrix} \text{Matrix} \\ 5 & 0 & 0 & 0 & 0 \\ \text{Alien} \\ \text{Serenity} \\ \text{Casablanca} \\ \text{Amelie} \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix} = \begin{bmatrix} \text{SciFi-concept} \\ 2.8 & 0.6 \end{bmatrix}$$

movie-to-concept factors (V)

Case study: How to query?

- How would the user d that rated ('Alien', 'Serenity') be handled?

$$d_{\text{concept}} = d V$$

E.g.:

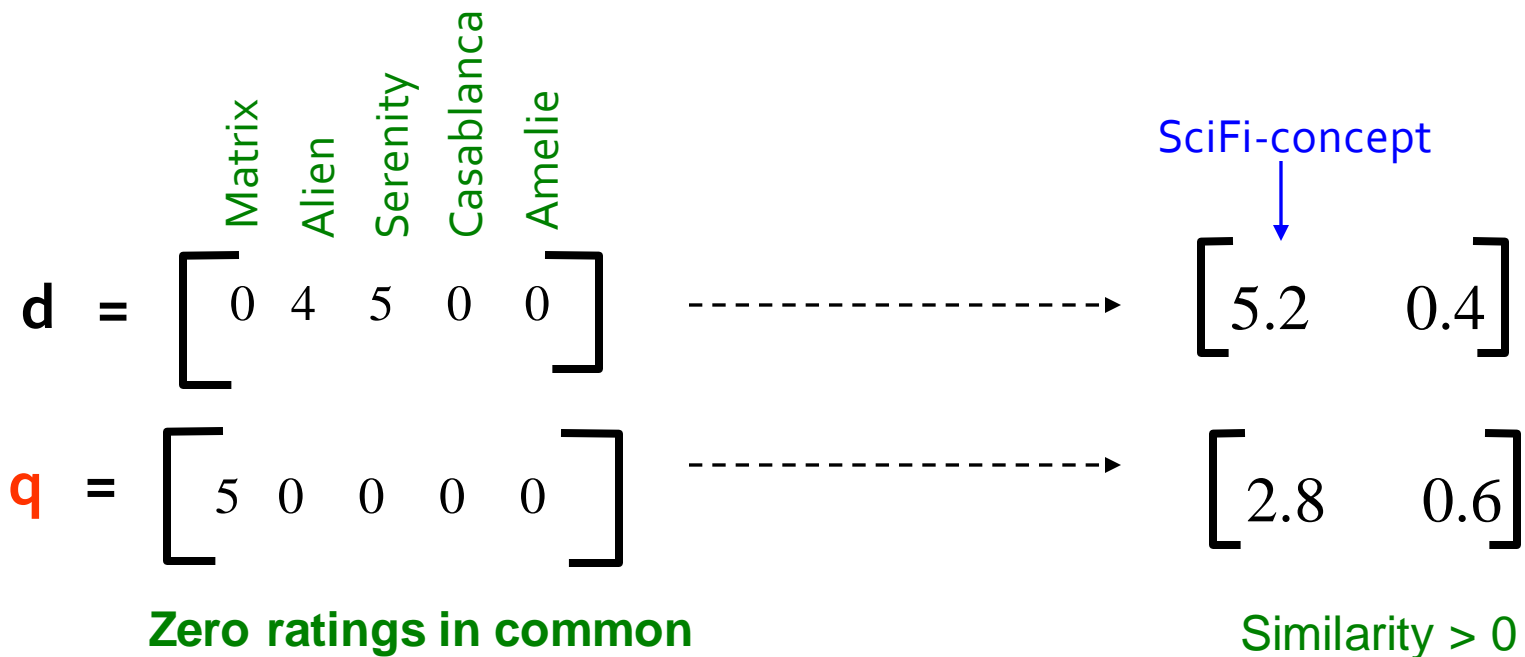
$$d = \begin{bmatrix} \text{Matrix} \\ 0 & 4 & 5 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} \text{Alien} \\ \text{Serenity} \\ \text{Casablanca} \\ \text{Amelie} \end{bmatrix} \times \begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix} = \begin{bmatrix} 5.2 & 0.4 \end{bmatrix}$$

SciFi-concept

movie-to-concept factors (V)

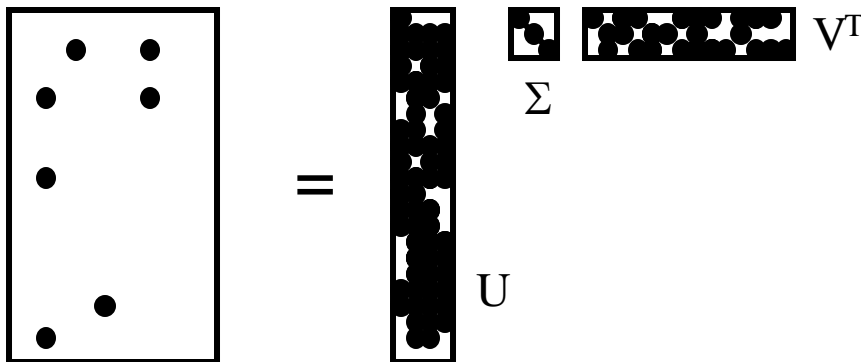
Case study: How to query?

- **Observation:** User d that rated ('*Alien*', '*Serenity*') will be **similar** to user q that rated ('*Matrix*'), although d and q have **zero ratings in common!**



SVD: Drawbacks

- + **Optimal low-rank approximation**
in terms of Frobenius norm
- **Interpretability problem:**
 - A singular vector specifies a linear combination of all input columns or rows
- **Lack of sparsity:**
 - Singular vectors are **dense!**



CUR Decomposition

Sparsity

- It is common for the matrix A that we wish to decompose to be very sparse
- But U and V from a SVD decomposition will **not** be sparse
- **CUR** decomposition solves this problem by using only (randomly chosen) rows and columns of A

CUR Decomposition

Frobenius norm:
 $\|X\|_F = \sqrt{\sum_{ij} X_{ij}^2}$

- Goal: Express A as a product of matrices C, U, R
Make $\|A - C \cdot U \cdot R\|_F$ small
- “Constraints” on C and R :

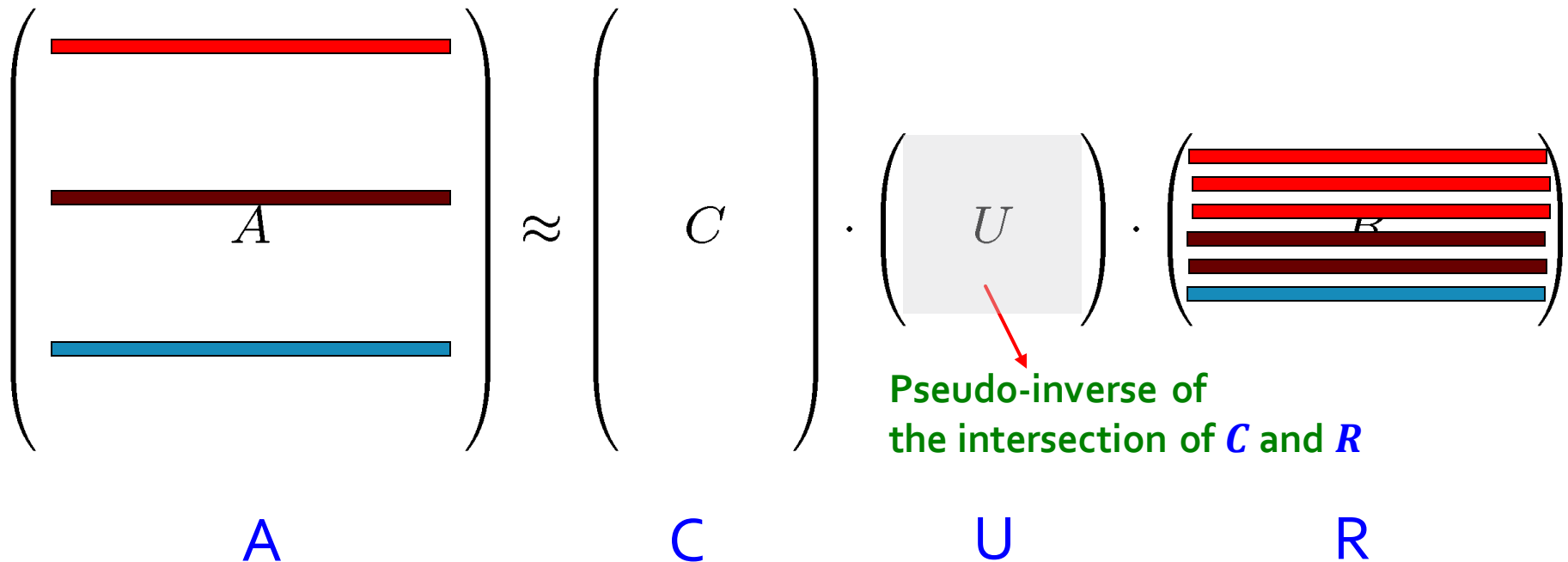
$$\left(\begin{array}{c} \text{red bar} \\ \text{blue bar} \\ \text{dark red bar} \end{array} \right) \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \left(\begin{array}{c} \\ \\ \\ \end{array} \right) \approx \left(\begin{array}{c} \text{red bar} \\ \text{red bar} \\ \text{red bar} \\ \text{blue bar} \\ \text{dark red bar} \\ \text{dark red bar} \end{array} \right) \cdot \left(\begin{array}{c} \\ \\ \\ \end{array} \right) \cdot \left(\begin{array}{c} \\ \\ \\ \end{array} \right)$$

$A \qquad C \qquad U \qquad R$

CUR Decomposition

Frobenius norm:
 $\|X\|_F = \sqrt{\sum_{ij} X_{ij}^2}$

- Goal: Express A as a product of matrices C, U, R
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Computing U

- Let W be the “intersection” of sampled columns C and rows R

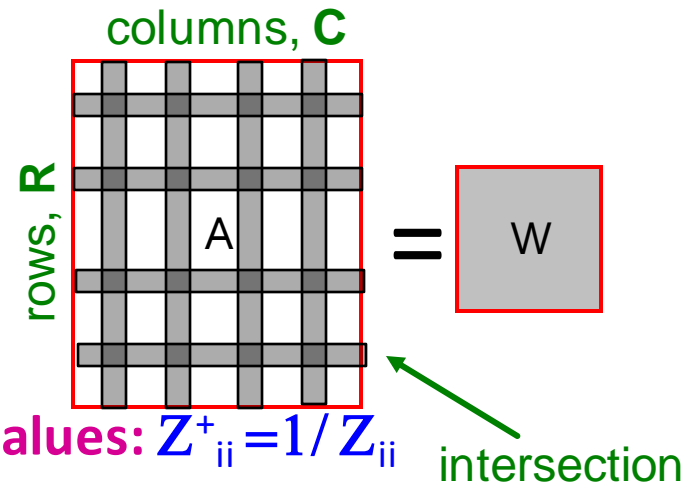
- Def: W^+ is the **pseudoinverse**

- Let SVD of $W = X Z Y^T$

- Then: $W^+ = Y Z^+ X^T$

- Z^+ : reciprocals of non-zero singular values: $Z^+_{ii} = 1/Z_{ii}$

- Let: $U = Y (Z^+)^2 X^T$



Why the intersection? These are high magnitude numbers

Why pseudoinverse works?

$$W = X Z Y^T \text{ then } W^{-1} = (Y^T)^{-1} Z^{-1} X^{-1}$$

$$\text{Due to orthonormality: } X^{-1} = X^T, \quad Y^{-1} = Y^T$$

$$\text{Since } Z \text{ is diagonal } Z^{-1} = 1/Z_{ii}$$

Thus, if W is nonsingular, pseudoinverse is the true inverse

Which Rows and Columns?

- To decrease the expected error between A and its decomposition, we must pick rows and columns in a nonuniform manner
- The **importance** of a row or column of A is the **square of its Frobenius norm**
 - That is, the sum of the squares of its elements.
- When picking rows and columns, the probabilities must be proportional to importance
- **Example:** $[3,4,5]$ has importance 50, and $[3,0,1]$ has importance 10, so pick the first 5 times as often as the second

CUR: Row Sampling Algorithm

- Sampling columns (similarly for rows):

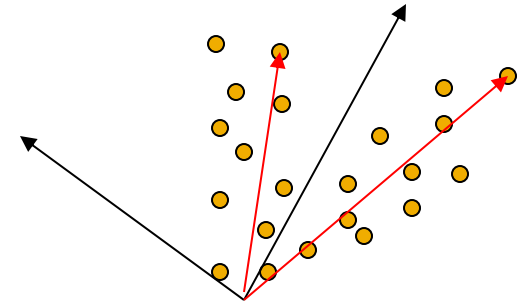
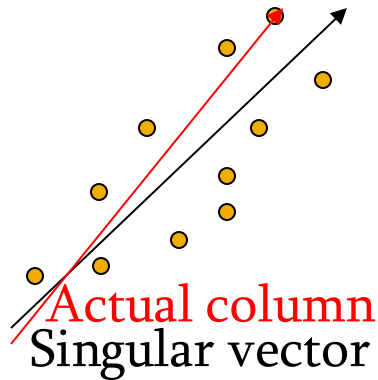
Input: matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, sample size c

Output: $\mathbf{C}_d \in \mathbb{R}^{m \times c}$

1. for $x = 1 : n$ [column distribution]
2. $P(x) = \sum_i \mathbf{A}(i, x)^2 / \sum_{i,j} \mathbf{A}(i, j)^2$
3. for $i = 1 : c$ [sample columns]
4. Pick $j \in 1 : n$ based on distribution $P(x)$
5. Compute $\mathbf{C}_d(:, i) = \mathbf{A}(:, j) / \sqrt{cP(j)}$

Note this is a randomized algorithm, same column can be sampled more than once

Intuition



- **Rough and imprecise intuition behind CUR**
 - CUR is more likely to pick points away from the origin
 - Assuming smooth data with no outliers these are the directions of maximum variation
- **Example:** Assume we have 2 clouds at an angle
 - SVD dimensions are orthogonal and thus will be in the middle of the two clouds
 - CUR will find the two clouds (but will be redundant)

CUR: Provably good approx. to SVD

- **For example:**

- Select $c = O\left(\frac{k \log k}{\varepsilon^2}\right)$ columns of A using **ColumnSelect** algorithm (slide 56)

- Select $r = O\left(\frac{k \log k}{\varepsilon^2}\right)$ rows of A using **RowSelect** algorithm (slide 56)

- Set $U = Y (Z^+)^2 X^T$

- **Then:** $\overset{\text{CUR error}}{\|A - CUR\|_F} \leq (2 + \varepsilon) \overset{\text{SVD error}}{\|A - A_K\|_F}$
with probability 98%

In practice: Pick $4k$ cols/rows for a “rank- k ” approximation

CUR: Pros & Cons

+ Easy interpretation

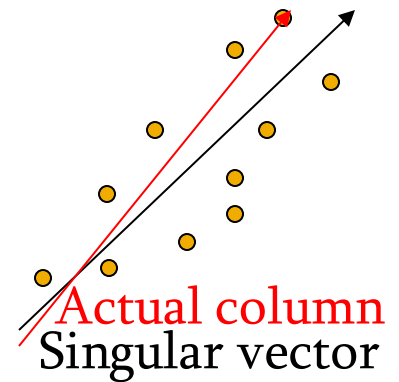
- Since the basis vectors are actual columns and rows

+ Sparse basis

- Since the basis vectors are actual columns and rows

- Duplicate columns and rows

- Columns of large norms will be sampled many times



SVD vs. CUR

sparse and small

$$\text{SVD: } A = U \Sigma V^T$$

Huge but sparse Big and dense

dense but small

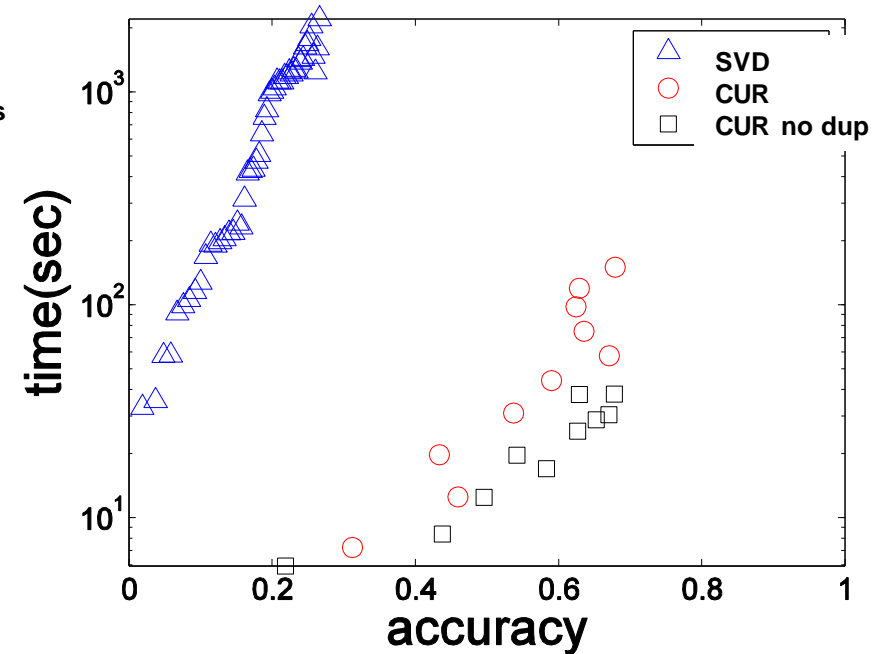
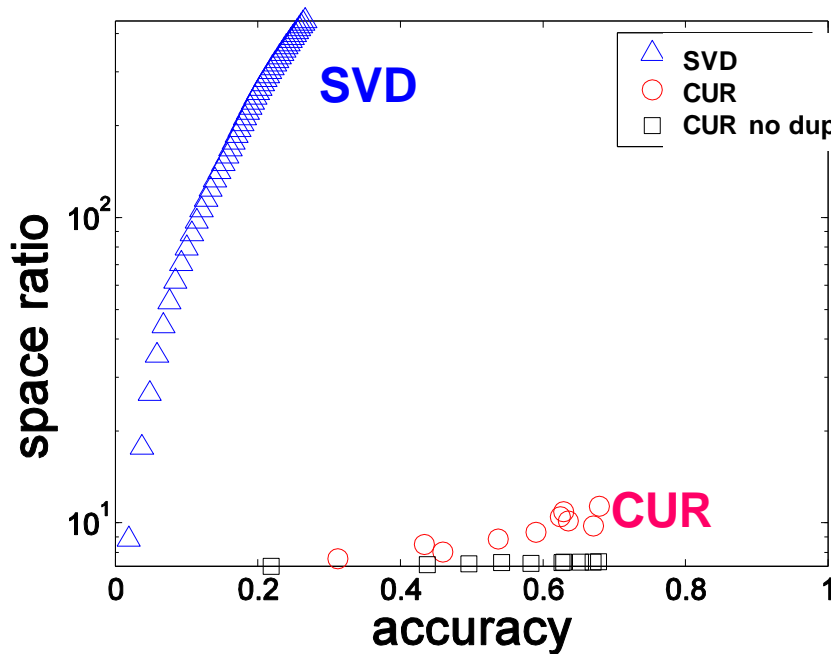
$$\text{CUR: } A = C U R$$

Huge but sparse Big but sparse

SVD vs. CUR: Simple Experiment

- **DBLP bibliographic data**
 - Author-to-conference big sparse matrix
 - A_{ij} : Number of papers published by author i at conference j
 - 428K authors (rows), 3659 conferences (columns)
 - **Very sparse**
- **Want to reduce dimensionality**
 - How much time does it take?
 - What is the reconstruction error?
 - How much space do we need?

Results: DBLP- big sparse matrix



- **Accuracy:**
 - 1 – relative sum squared errors
- **Space ratio:**
 - #output matrix entries / #input matrix entries
- **CPU time**

Sun, Faloutsos: *Less is More: Compact Matrix Decomposition for Large Sparse Graphs*, SDM '07.